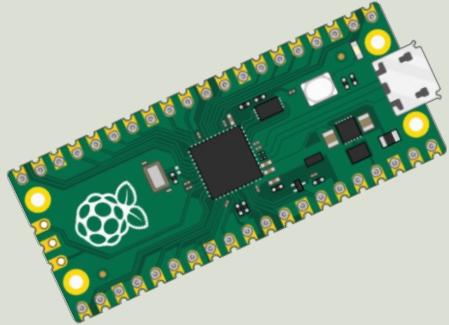


<https://www.halvorsen.blog>



Raspberry Pi Pico

TMP36 Temperature Sensor



Hans-Petter Halvorsen

Contents

- Introduction
- Raspberry Pi Pico
 - Thonny Python Editor
 - MicroPython
- TMP36 Temperature Sensor



<https://www.halvorsen.blog>



Introduction

Hans-Petter Halvorsen

[Table of Contents](#)

Introduction

- In this Tutorial we will read values from a **TMP36** Temperature Sensor.
- We will use a **Raspberry Pi Pico** and **MicroPython**.
- We will use the **Thonny** Python Editor which has built-in support for the Raspberry Pi Pico hardware/MicroPython firmware.

What do you need?

- Raspberry Pi Pico
- A Micro-USB cable
- A PC with Thonny Python Editor (or another Python Editor)
- Breadboard
- Electronics Components like LED, Resistors, Jumper wires, etc.
- TMP36 Temperature Sensor



<https://www.halvorsen.blog>



Raspberry Pi Pico

Hans-Petter Halvorsen

[Table of Contents](#)

Raspberry Pi Pico

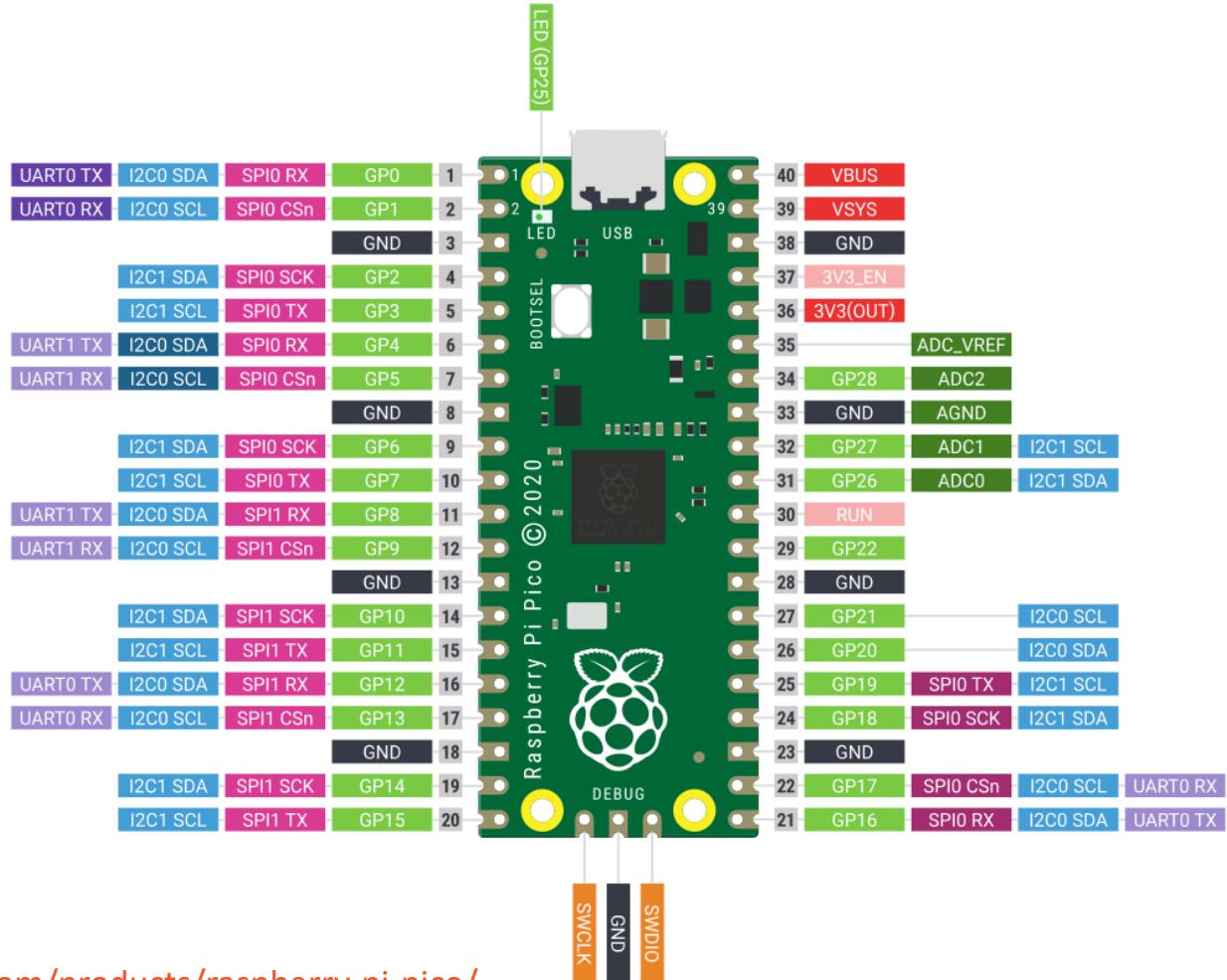
- Raspberry Pi Pico is a microcontroller board developed by the Raspberry Pi Foundation
- Raspberry Pi Pico has similar features as Arduino devices
- Raspberry Pi Pico is typically used for Electronics projects, IoT Applications, etc.
- You typically use MicroPython, which is a downscaled version of Python, in order to program it



<https://www.raspberrypi.com/products/raspberry-pi-pico/>

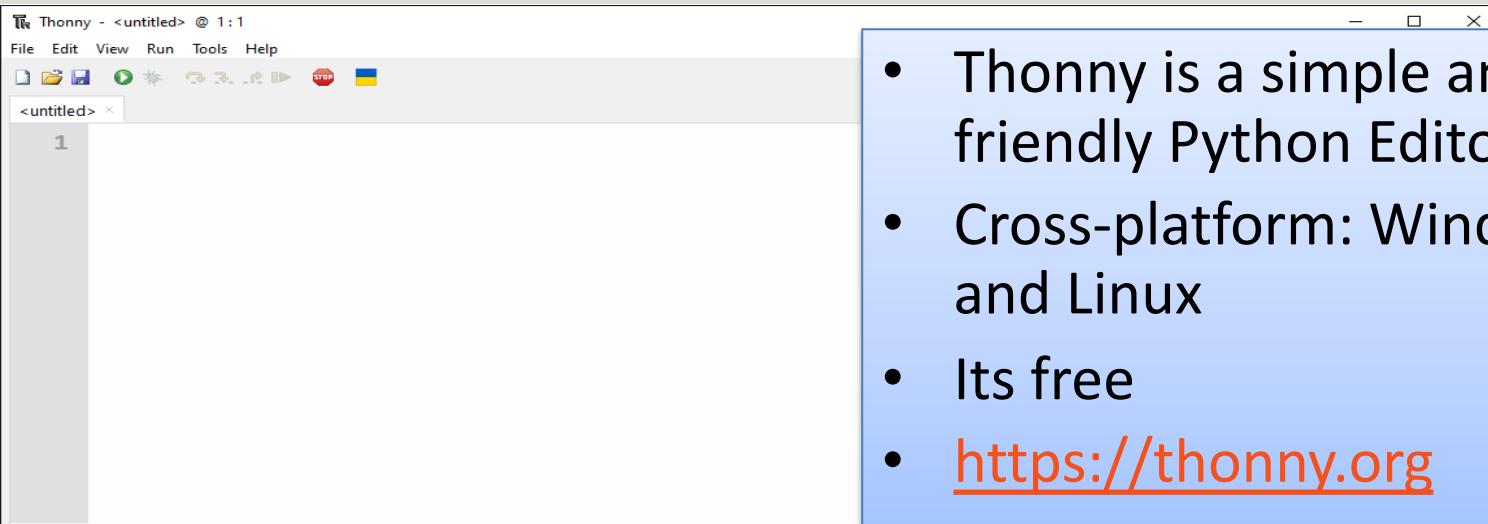
<https://projects.raspberrypi.org/en/projects/getting-started-with-the-pico>

Pico Pinout



<https://www.raspberrypi.com/products/raspberry-pi-pico/>

Thonny



- Thonny is a simple and user-friendly Python Editor
- Cross-platform: Windows, macOS and Linux
- Its free
- <https://thonny.org>

MicroPython

- MicroPython is a downscaled version of Python
- It is typically used for Microcontrollers and constrained systems

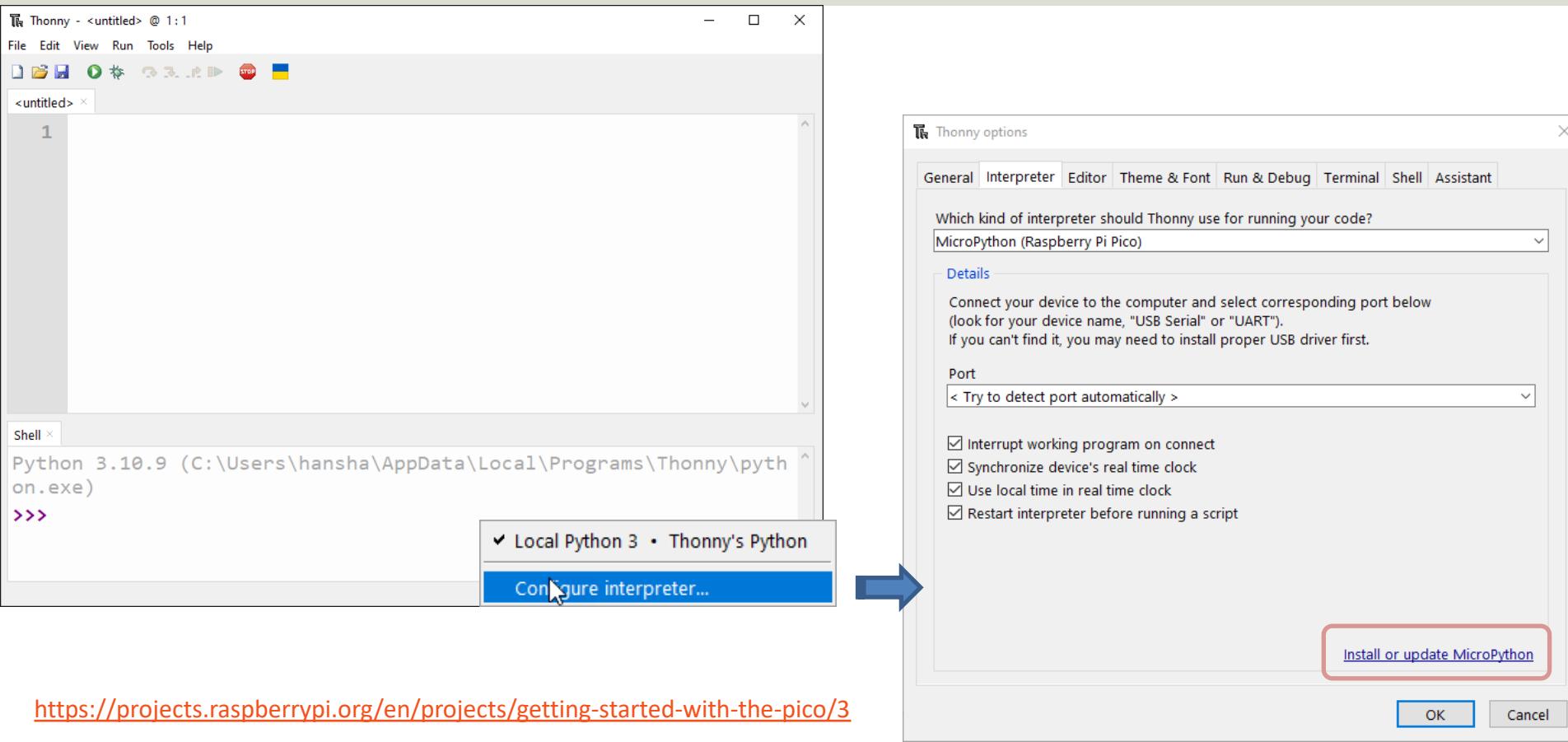
<https://docs.micropython.org/en/latest/index.html>

<https://micropython.org>

MicroPython Firmware

- The first time you need to install the MicroPython Firmware on your Raspberry Pi Pico
- You can install the MicroPython Firmware manually or you can use the Thonny Editor

Install MicroPython Firmware using Thonny



<https://projects.raspberrypi.org/en/projects/getting-started-with-the-pico/3>

<https://www.halvorsen.blog>



TMP36 Temperature Sensor

Hans-Petter Halvorsen

[Table of Contents](#)

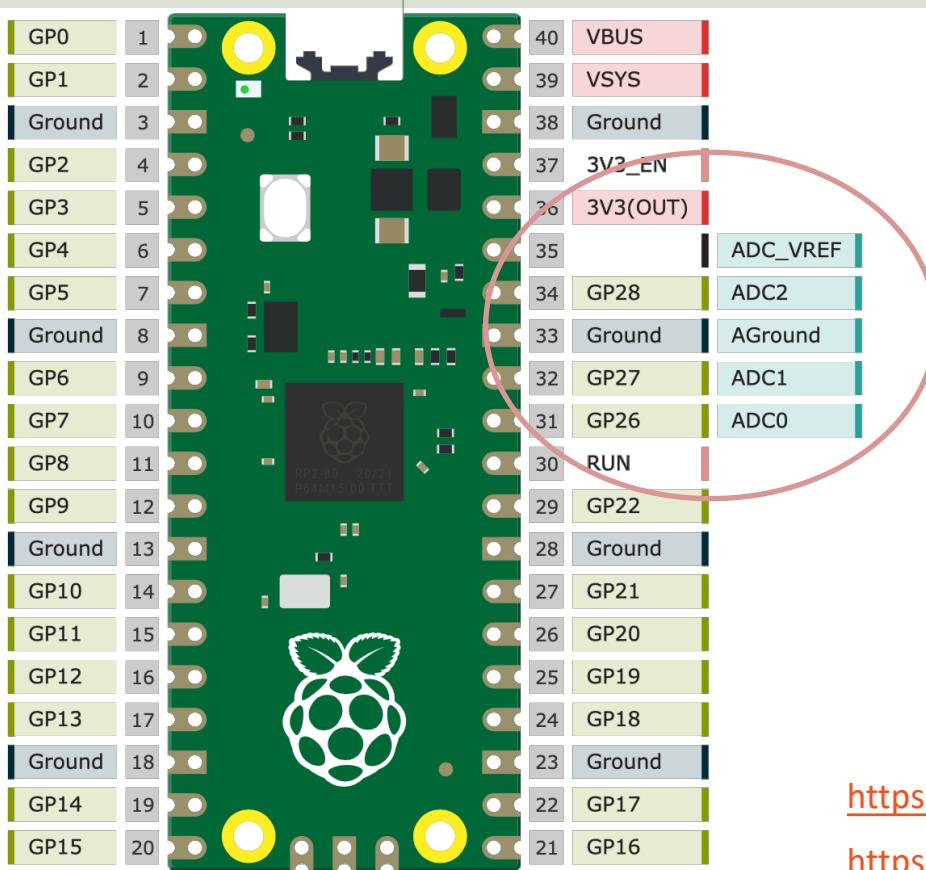
TMP36 Temperature Sensor



A Temperature sensor like TM36 use a solid-state technique to determine the temperature.

They use the fact as temperature increases, the voltage across a diode increases at a known rate.

Analog Values with Pico



Raspberry Pi Pico has
3 Analog Inputs (ADC)

ADC 0 – Pin 26

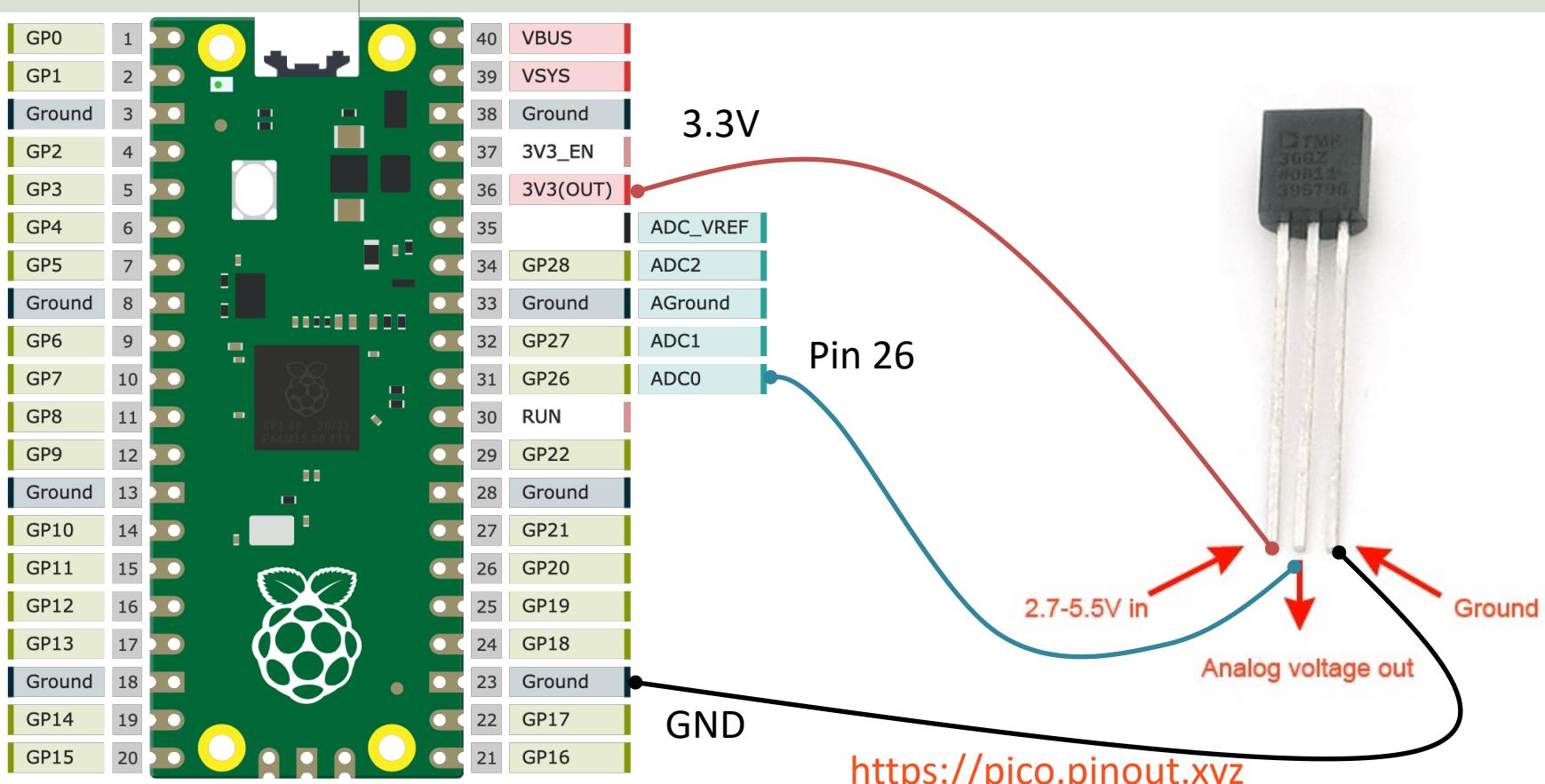
ADC 1 – Pin 27

ADC 2 – Pin 28

<https://pico.pinout.xyz>

<https://docs.micropython.org/en/latest/library/machine.ADC.html>

TMP36 Wiring



Main Code Structure

1. Initialization.
2. Read from ADC (Analog to Digital Converter) using “read_u16()” function.
3. Convert raw ADC Value (0-65535) to Voltage Value (0-3.3v). The built-in ADC has 16 resolution.
4. Convert from Voltage Value to Temperature in degrees Celsius. Use information from the TMP36 Temperature Sensor Datasheet.

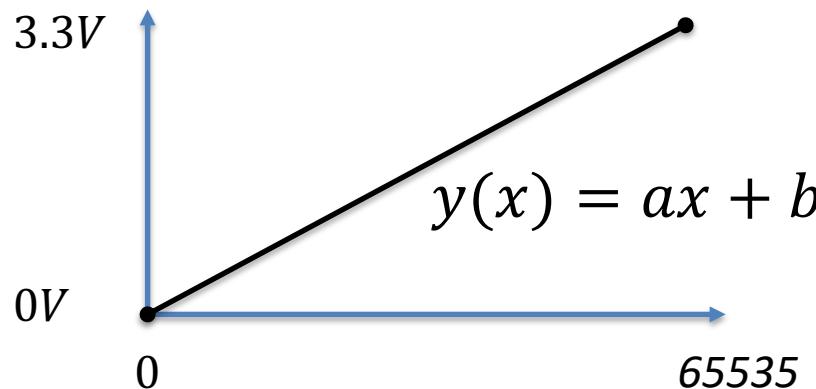
ADC Value to Voltage Value

Analog Pins: The built-in Analog-to-Digital Converter (ADC) on Pico is 16bit, producing values from 0 to 65535.

The `read_u16()` function gives a value between 0 and 65535. It must be converted to a Voltage Signal 0 - 3.3v

$$\text{ADC} = 0 \rightarrow 0\text{v}$$

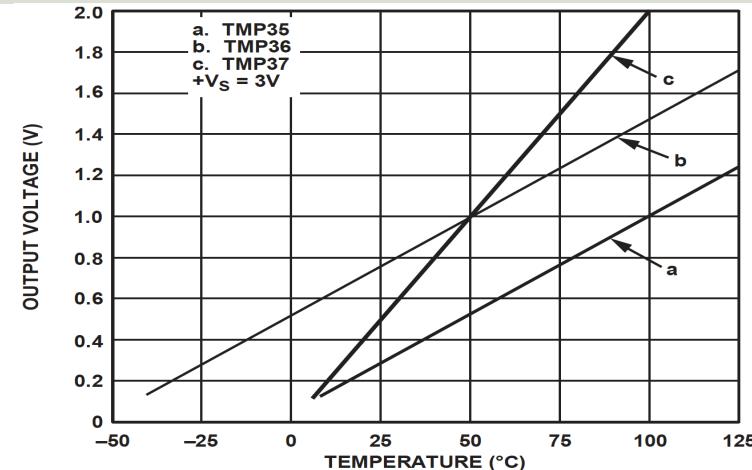
$$\text{ADC} = 65535 \rightarrow 3.3\text{v}$$



This gives the following conversion formula:

$$y(x) = \frac{3.3}{65535} x$$

Voltage to degrees Celsius



This gives:

$$y - 25 = \frac{50 - 25}{1 - 0.75} (x - 0.75)$$

Then we get the following formula:

$$y = 100x - 50$$

Convert form Voltage (V) to degrees Celsius
From the **Datasheet** we have:

$$(x_1, y_1) = (0.75V, 25^\circ C)$$
$$(x_2, y_2) = (1V, 50^\circ C)$$

There is a linear relationship between
Voltage and degrees Celsius:

$$y = ax + b$$

We can find a and b using the following
known formula:

$$y - y_1 = \frac{y_2 - y_1}{x_2 - x_1} (x - x_1)$$

Main Code Structure

1. Initialization

```
adcpin = 26
```

```
tmp36 = ADC(adcpin)
```

2. Read from ADC:

```
adc_value = tmp36.read_u16()
```

3. Convert raw ADC Value (0-65535) to Voltage Value (0-3.3v):

```
volt = (3.3/65535)*adc_value
```

4. Convert from Voltage Value to Temperature in degrees Celsius:

```
degC = (100*volt)-50
```

TMP36 Example

```
from machine import ADC
from time import sleep

adcpin = 26
tmp36 = ADC(adcpin)

while True:
    adc_value = tmp36.read_u16()
    volt = (3.3/65535)*adc_value
    degC = (100*volt)-50
    print(round(degC, 1))
    sleep(5)
```

File Edit View Run Tools Help



tmp36.py x

```
1 from machine import ADC
2 from time import sleep
3
4 adcpin = 26
5 tmp36 = ADC(adcpin)
6
7 while True:
8     adc_value = tmp36.read_u16()
9     #print(adc_value)
10
11     volt = (3.3/65535)*adc_value
12     #print(volt)
13
14     degC = (100*volt)-50
15     print(round(degC, 1))
16
17     sleep(5)
```

Shell x

>>> %Run -c \$EDITOR_CONTENT

```
25.7
25.6
27.5
30.3
28.8
27.2
26.8
26.7
```

TM36 Code v2

```
from machine import ADC
from time import sleep

adcpin = 26
tmp36 = ADC(adcpin)

def ReadTemperature():
    adc_value = tmp36.read_u16()
    volt = (3.3/65535)*adc_value
    degC = (100*volt)-50
    return degC

while True:
    degC = ReadTemperature()
    print(round(degC, 1))
    sleep(5)
```

TMP36 Code V3

```
from machine import ADC
```

TemperatureSensors.py

```
class Tmp36Sensor:  
    def __init__(self, pin):  
        self.tmp36 = ADC(pin)  
  
    def ReadTemperature(self):  
        adc_value = self.tmp36.read_u16()  
        volt = (3.3/65535)*adc_value  
        degC = (100*volt)-50  
        return round(degC, 1)
```

```
from TemperatureSensors import Tmp36Sensor  
from time import sleep  
  
adcpin = 26  
tmp36 = Tmp36Sensor(adcpin)  
  
while True:  
    degC = tmp36.ReadTemperature()  
    print(degC)  
    sleep(5)
```

<https://www.halvorsen.blog>



PicoZero

Hans-Petter Halvorsen

[Table of Contents](#)

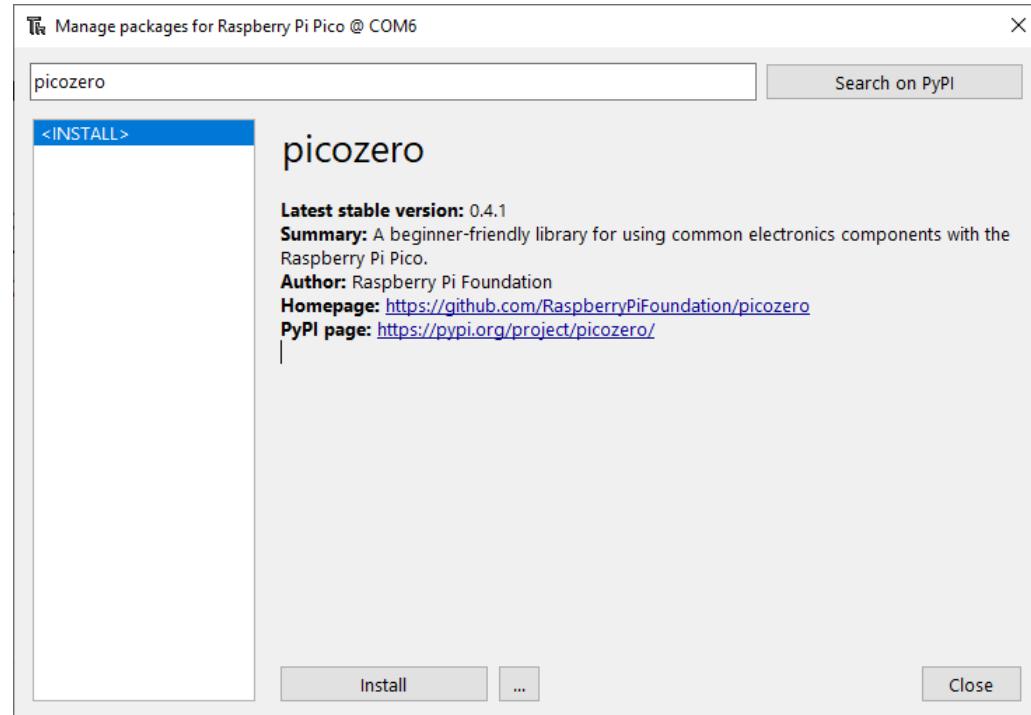
PicoZero

- The **picozero** Python Library is intended to be a beginner-friendly library for using common electronics components with the Raspberry Pi Pico
- It can be used instead of the machine Library in many cases
- You install it like an ordinary Python Library using “`pip install picozero`” or from the “Manage Packages” window in the Thonny editor

<https://pypi.org/project/picozero/>

<https://picozero.readthedocs.io>

<https://github.com/RaspberryPiFoundation/picozero>



PicoZero TemperatureSensor

latest

Search docs

CONTENTS:

- Getting started
- Recipes

⊕ picozero API

- ⊕ LED
- ⊕ DigitalLED
- ⊕ PWMLED
- ⊕ RGBLED
- ⊕ Buzzer
- ⊕ PWM_Buzzer
- ⊕ Speaker
- ⊕ Servo
- ⊕ Motor
- ⊕ Robot / Rover
- ⊕ DigitalOutputDevice
- ⊕ PWMOutputDevice
- ⊕ Button
- ⊕ Switch

TemperatureSensor / TempSensor / Thermistor

`class picozero.TemperatureSensor(pin, active_state=True, threshold=0.5, conversion=None)` [\[source\]](#)

Bases: `AnalogInputDevice`

Represents a TemperatureSensor, which outputs a variable voltage. The voltage can be converted to a temperature using a `conversion` function passed as a parameter.

Alias for `Thermistor` and `TempSensor`.

Parameters:

- `pin (int)` – The pin that the device is connected to.
- `active_state` – The active state of the device. If `True` (the default), the `AnalogInputDevice` will assume that the device is active when the pin is high and above the threshold. If `active_state` is `False`, the device will be active when the pin is low and below the threshold.
- `threshold (float)` – The threshold that the device must be above or below to be considered active. The default is 0.5.
- `conversion (float)` – A function that takes a voltage and returns a temperature.
e.g. The internal temperature sensor has a voltage range of 0.706V to 0.716V and would use the follow conversion function:

```
def temp_conversion(voltage):
    return 27 - (voltage - 0.706)/0.001721

temp_sensor = TemperatureSensor(pin, conversion=temp_conversion)
```

If `None` (the default), the `temp` property will return `None`.

PicoZeroTemp36

```
from picozero import TemperatureSensor
from time import sleep

def TempCelsius(voltage):
    tempC = (100*voltage)-50
    tempC = round(tempC,1)
    return tempC

pin = 26
tmp36 = TemperatureSensor(pin, conversion=TempCelsius)

while True:
    tempC = tmp36.temp
    print(tempC, "°C")

    sleep(5)
```

Raspberry Pi Pico Resources

- Raspberry Pi Pico:

<https://www.raspberrypi.com/products/raspberry-pi-pico/>

- Raspberry Pi Foundation:

[https://projects.raspberrypi.org/en/projects?hardware\[\]=%pico](https://projects.raspberrypi.org/en/projects?hardware[]=%pico)

- Getting Started with Pico:

<https://projects.raspberrypi.org/en/projects/getting-started-with-the-pico>

- MicroPython:

<https://docs.micropython.org/en/latest/index.html>

Hans-Petter Halvorsen

University of South-Eastern Norway

www.usn.no

E-mail: hans.p.halvorsen@usn.no

Web: <https://www.halvorsen.blog>

